Feature	Xcos	Simulink	OpenRTDynamics
Continuous-	Yes	Yes	only by embedding
time simulati-			into Xcos (planned
on			Simulink)
Realisation	code generation	code generation	real-time capable
of Real-time			interpreter
Programms			
Description	GUI-based Blocks	GUI-based Blocks	textural description
language			using Scilab
Ability to ob-	superblocks	subsystems,	superblocks for
tain well struc-			sharing code, con-
tured code			ditional definition
			(like compiler
			flags), for loops,
			, allows to build
			powerful macros
Possible Target	Rtai, Real-time pre-	Nearly any target	Linux RT-
Systems	emption, with much		Preemption and
	effort more		normal Linux:
			PC-based Linux,
			Android, embed-
			ded ARM devices

Feature	Xcos	Simulink	OpenRTDynamics
Communication with RT- Programms	only if Rtai is used	Yes	Yes
Implementation	using events (red	Stateflow, separati-	state machines that
of Logic struc-	lines) and signals;	on of continuous	allow to combine
tures	cumbersome and much effort	parts and logic	continuous parts and logic; low im- plementation effort; start/stop/reset of superblocks
Multiple Threads with a	No	allows to start "Tasks"	Yes: shared me- mory, ring buffer,
separate main		Tublic	events for commu-
loop in each			nication
Time basis of the main loop	regular timer	regular timer	irregular time in- tervals possible, synchronisation to events e.g.: sensor data available, network packets arrived

Comparison to other systems - III

Feature	Xcos	Simulink	OpenRTDynamics
Including Scilab/Matlab Code into the RT-Program	No	Code based a subset of the Mat- lab language can be compiled to C-Code	Yes: embedded Scilab interpre- ter, however no-deterministic execution time. Suggested to only use in separated threads
Replacing Co- de portions of the RT- Program while it is running	No	No	Yes, the code of spe- cially marked su- perblocks can be exchanged. The em- bedded Scilab inter- preter can online- compile new super- blocks
Automating laboratory ex- periments with less effort	No	Not sure	Yes, macros that greatly simplify automation tasks using Scilab-Code and replaceable superblocks are available